

UNIVERSITY OF TWENTE.

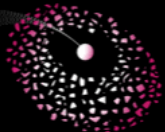
Formal Methods & Tools.

Confluence Reduction for Markov Automata

Mark Timmer
April 4, 2013

FMT Lunchmeeting

*Joint work with
Jaco van de Pol and Mariëlle Stoelinga*



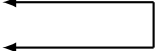
The overall goal: efficient and expressive modelling

Specifying systems with

- Nondeterminism ← LTSs
- Probability ← DTMCs
- Stochastic timing ← CTMCs

The overall goal: efficient and expressive modelling

Specifying systems with

- Nondeterminism
 - Probability
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- Probabilistic Automata (PAs)
- The diagram consists of a rectangular box with the text "Probabilistic Automata (PAs)" to its right. From the left side of the box, two horizontal arrows point to the left, one towards "Nondeterminism" and one towards "Probability".

The overall goal: efficient and expressive modelling

Specifying systems with


- Nondeterminism
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Interactive Markov Chains (IMCs)

A diagram consisting of a vertical rectangular box on the right side. From the top-left corner of the box, a horizontal arrow points left towards the text 'Nondeterminism'. From the bottom-left corner of the box, a horizontal arrow points left towards the text 'Stochastic timing'. The right side of the box is open.

The overall goal: efficient and expressive modelling

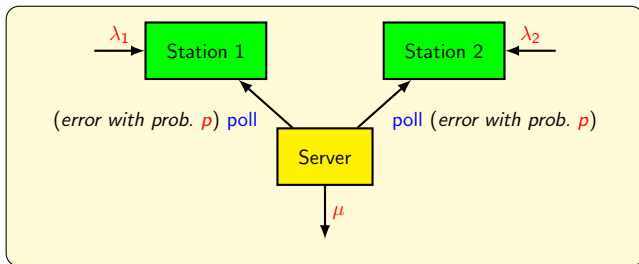
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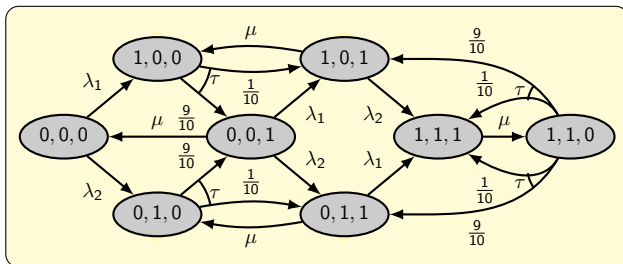
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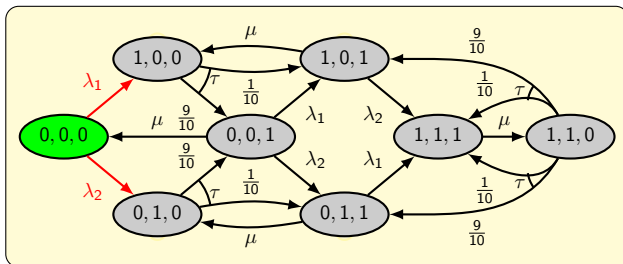
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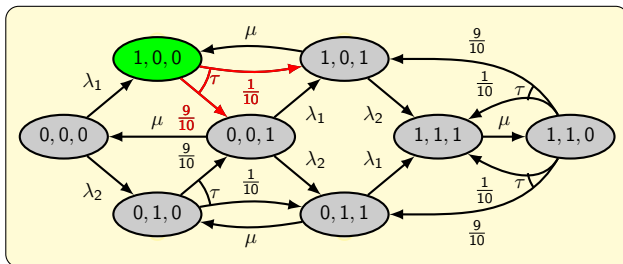
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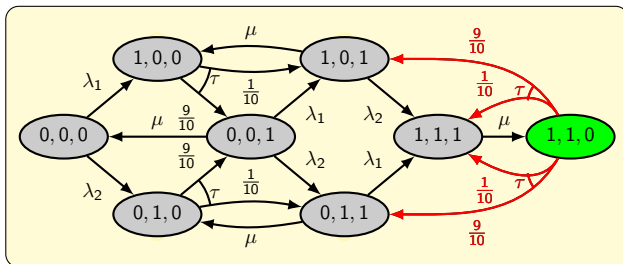
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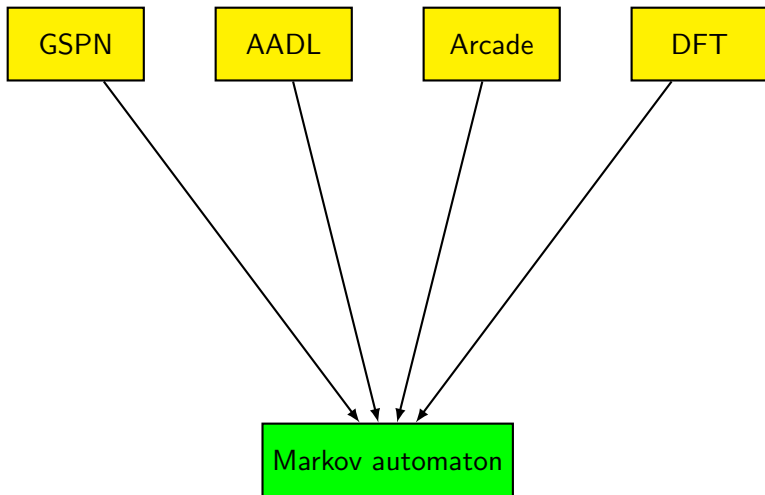
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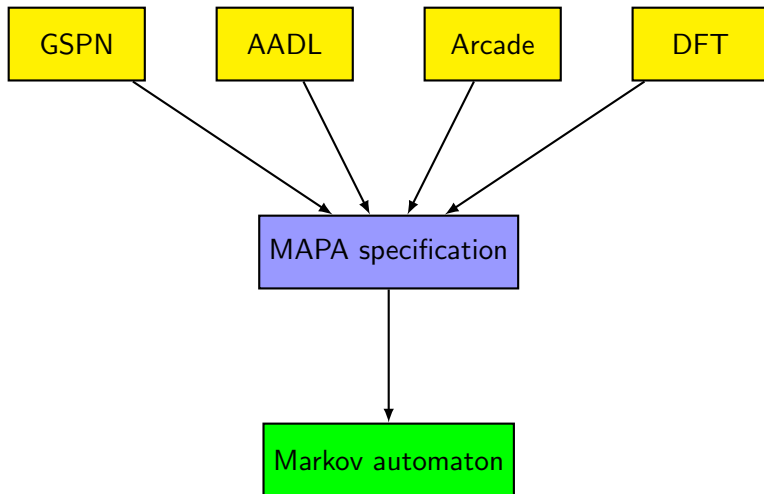
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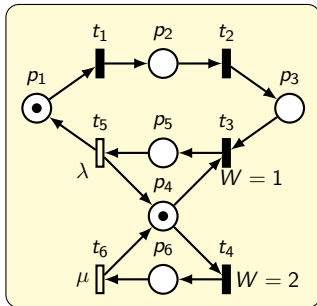
Higher-level formalisms that can be mapped to MAs



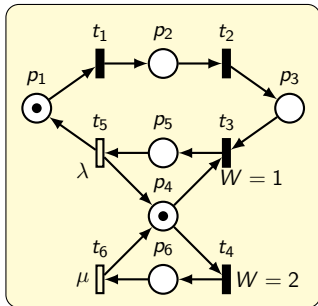
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Higher-level formalisms mapped to MAs



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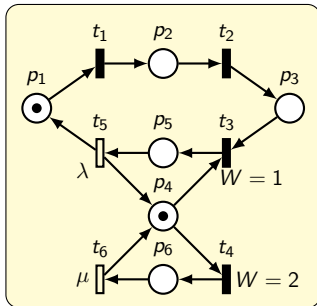


MAPA specification

$System(P_1 : \mathbb{N}, P_2 : \mathbb{N}, P_3 : \mathbb{N}, P_4 : \mathbb{N}, P_5 : \mathbb{N}, P_6 : \mathbb{N}) =$

$$\begin{aligned}
 & P_1 \geq 1 \implies \tau \cdot System(P_1 - 1, P_2 + 1, P_3, P_4, P_5, P_6) \\
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Higher-level formalisms mapped to MAs

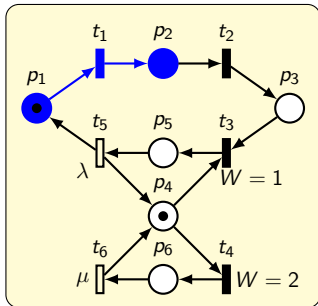


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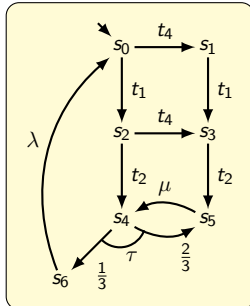
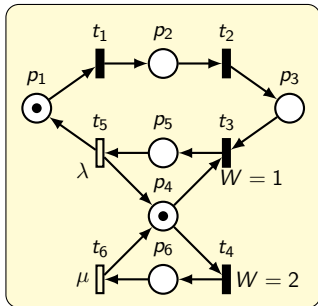


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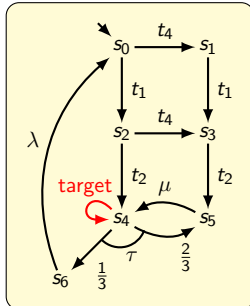
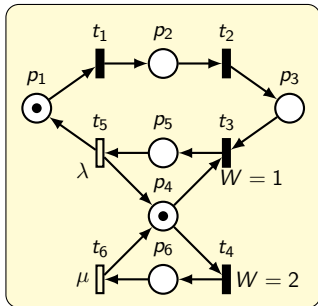


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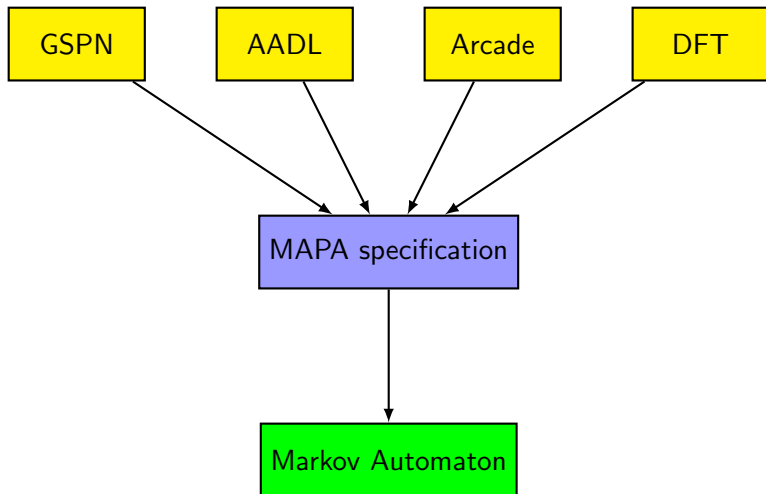


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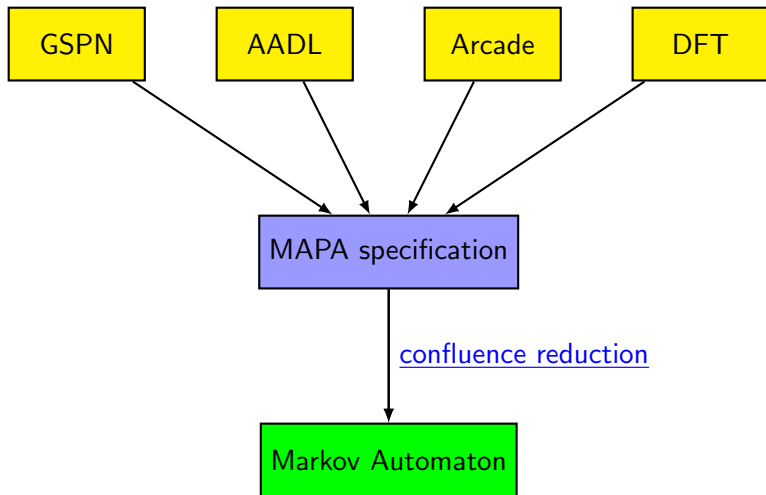
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Higher-level formalisms mapped to MAs



Higher-level formalisms mapped to MAs



Contents

- 1 Introduction
- 2 Confluence for Markov Automata
- 3 State Space Reduction Using Confluence
- 4 Symbolic Detection on MAPA Specifications
- 5 Implementation and Case Studies
- 6 Conclusions and Future Work

Invisible transitions connecting equivalent states

Invisible transitions in confluence reduction:

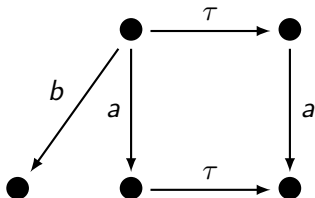
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Deterministic τ -steps **might** disable behaviour...

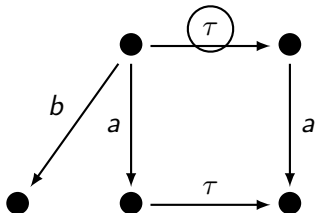


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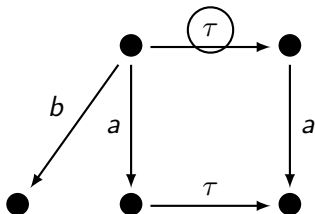
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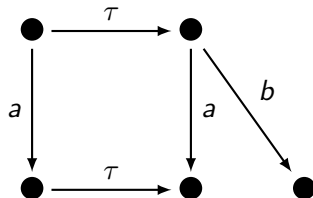
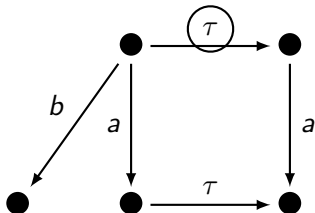
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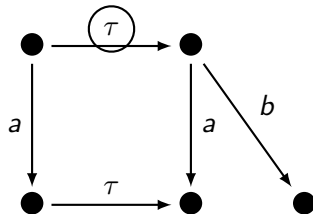
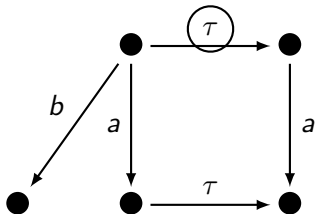
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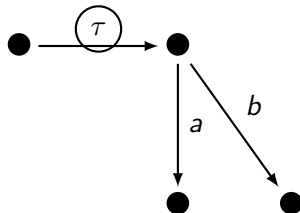
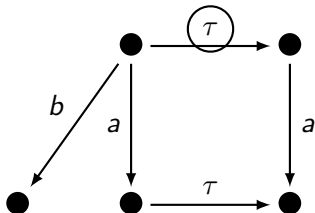
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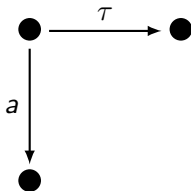
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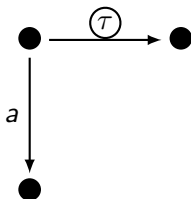


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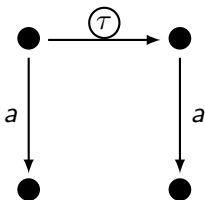


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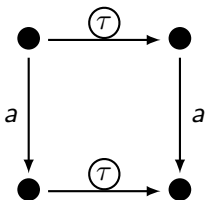


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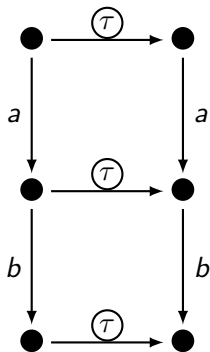


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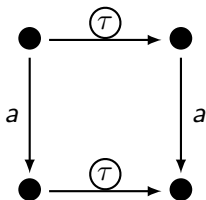


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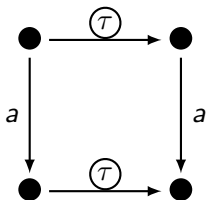


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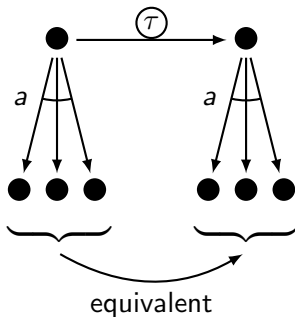
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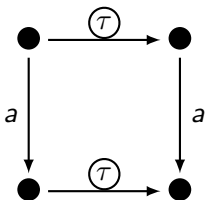


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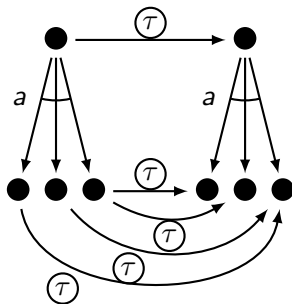
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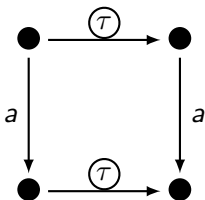


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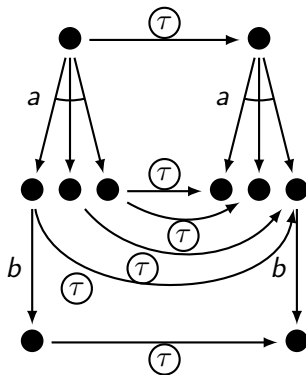
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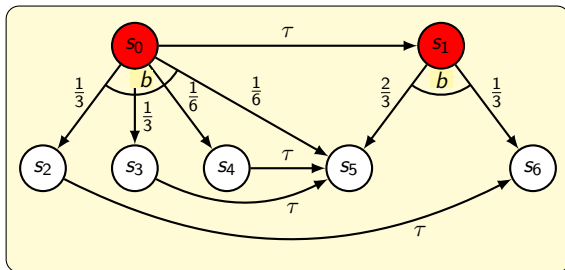
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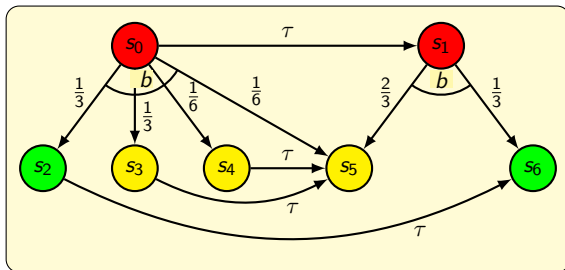
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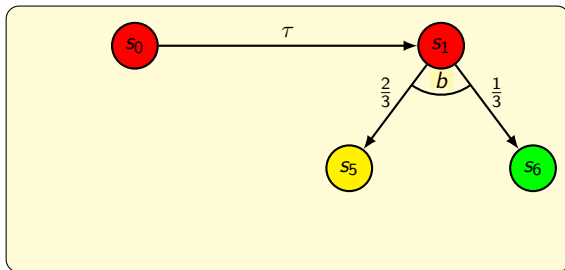
Probabilistic example



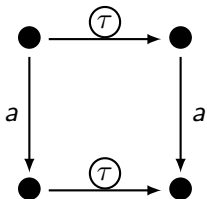
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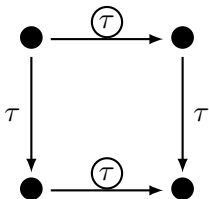
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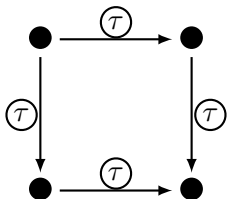
Problem with earlier definitions: no closure under union



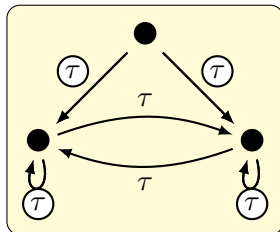
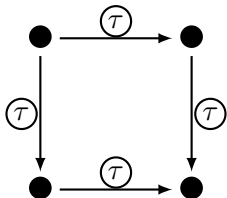
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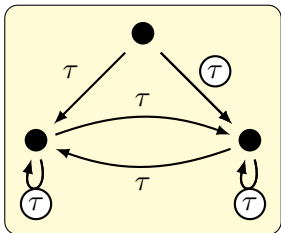
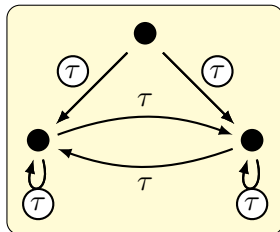
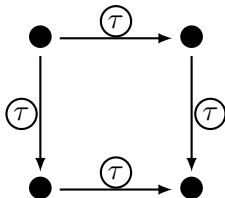
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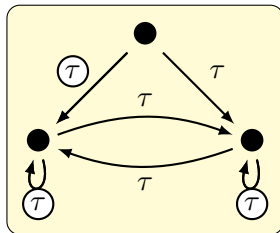
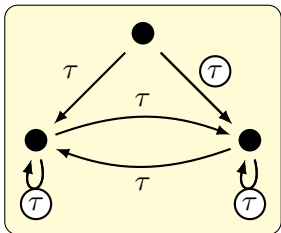
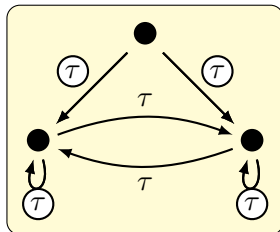
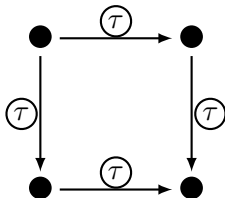
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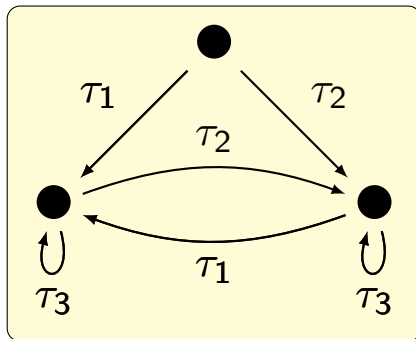
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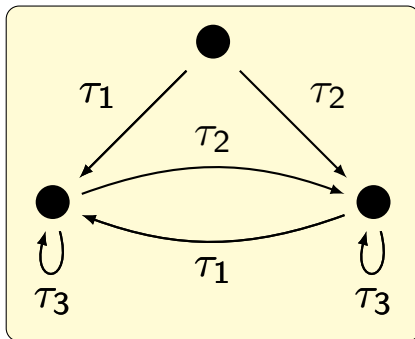
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Our solution: confluence classification

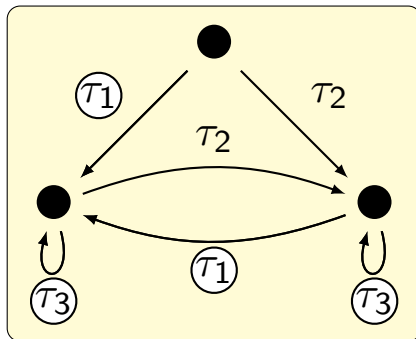


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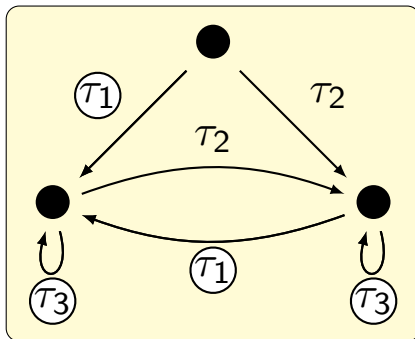
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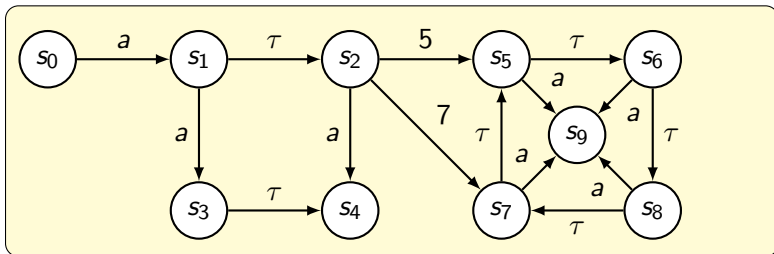
Our solution: confluence classification



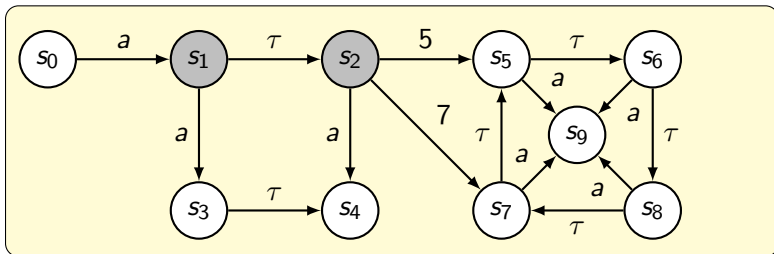
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Closure under unions is now really ensured.

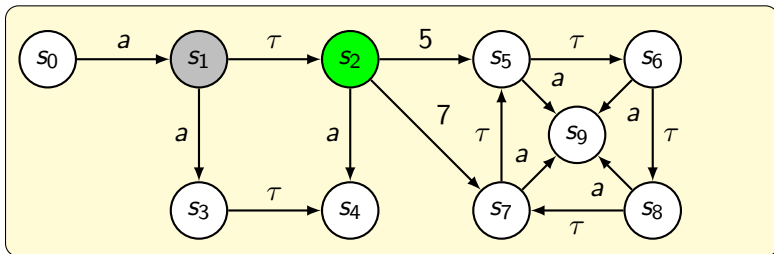
Representative map approach



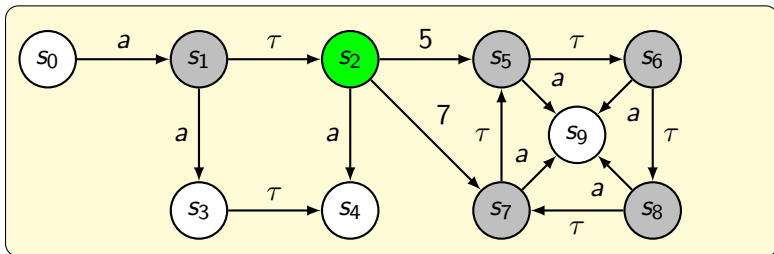
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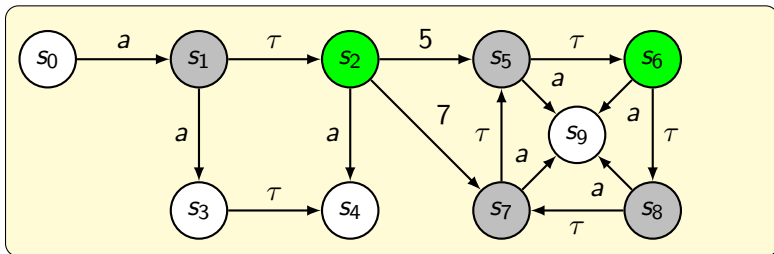
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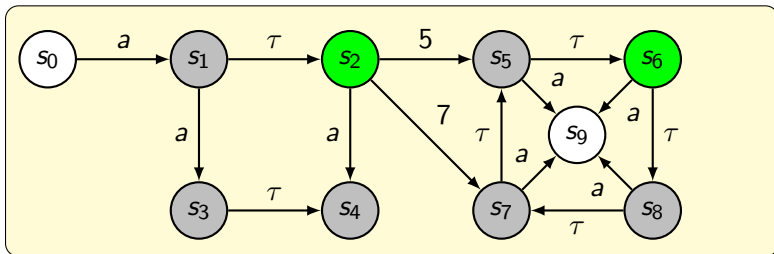
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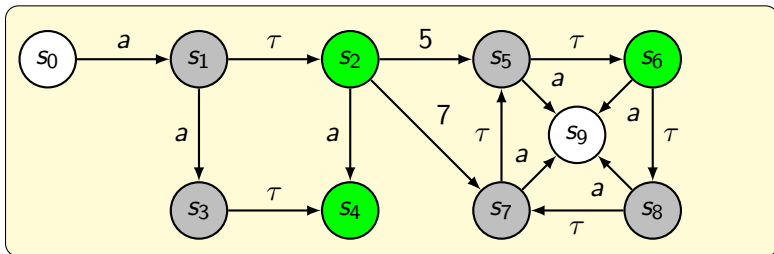
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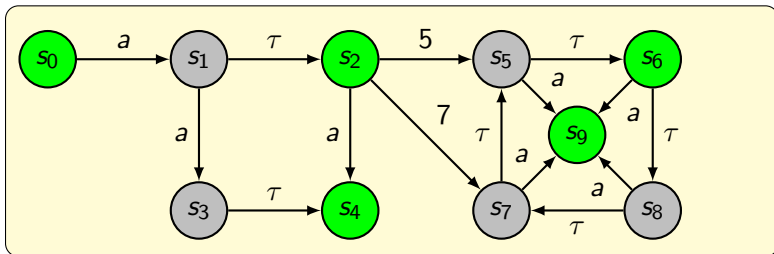
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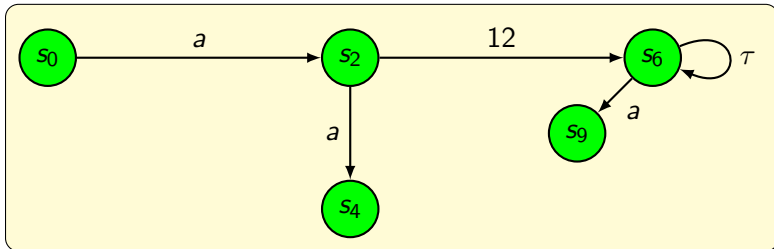
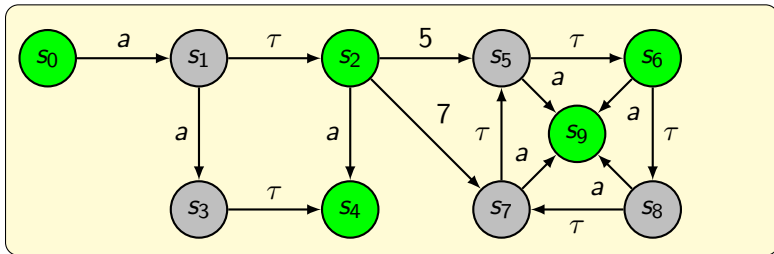
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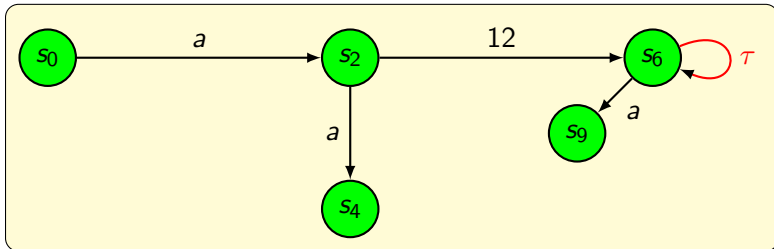
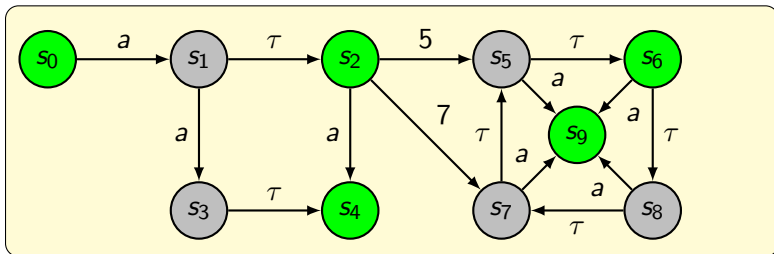
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A process algebra for Markov automata: MAPA

Specification language MAPA:

- Based on μ CRL (so [data](#)), with additional [probabilistic choice](#) and [Markovian rates](#)
- Semantics defined in terms of [Markov automata](#)
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$$p ::= Y(t) \mid c \Rightarrow p \mid p + p \mid \sum_{x:D} p \mid a(t) \bullet \sum_{x:D} f : p \mid (\lambda) \cdot p$$

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- Composibility via **parallel composition**, **encapsulation**, **hiding** and **renaming**

MLPPEs

We defined a special format for MAPA, the [MLPPE](#):

$$\begin{aligned}
 X(g : G) = & \sum_{i \in I} \sum_{d_i : D_i} c_i \Rightarrow a_i(\mathbf{b}_i) \sum_{e_i : E_i} f_i : X(\mathbf{n}_i) \\
 & + \sum_{j \in J} \sum_{d_j : D_j} c_j \Rightarrow (\lambda_j) \cdot X(\mathbf{n}_j)
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Example of an MLPPE

GSPN-generated MAPA specification

$$\begin{aligned}
 \text{System}(P_1 : \mathbb{N}, P_2 : \mathbb{N}, P_3 : \mathbb{N}, P_4 : \mathbb{N}, P_5 : \mathbb{N}, P_6 : \mathbb{N}) = & \\
 & P_1 \geq 1 \implies \tau \cdot \text{System}(P_1 - 1, P_2 + 1, P_3, P_4, P_5, P_6) \\
 & + P_2 \geq 1 \implies \tau \cdot \text{System}(P_1, P_2 - 1, P_3 + 1, P_4, P_5, P_6) \\
 & + P_5 \geq 1 \implies \lambda \cdot \text{System}(P_1 + 1, P_2, P_3, P_4 + 1, P_5 - 1, P_6) \\
 & + P_6 \geq 1 \implies \mu \cdot \text{System}(P_1, P_2, P_3, P_4 + 1, P_5, P_6 - 1) \\
 & + (P_3 \geq 1 \wedge P_4 \geq 1) \vee (P_4 \geq 1) \implies \tau \sum_{i:\{4,5\}} f : \\
 & \quad \text{System}(P_1, P_2, \text{if } i = 4 \text{ then } P_3 - 1 \text{ else } P_3, P_4 - 1, \\
 & \quad \quad \text{if } i = 4 \text{ then } P_5 + 1 \text{ else } P_5, \\
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Theorem

*Every specification (without unguarded recursion) can be **linearised** to an MLPPE, preserving strong bisimulation.*

Detecting confluence symbolically on MLPPEs

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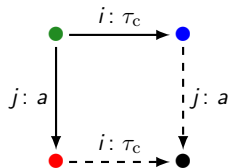
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 - They should not influence each other's probability expression
 - Their order should not influence the next state

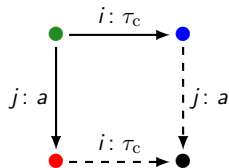
Heuristics for detecting confluence on MAPA

$$\begin{aligned}
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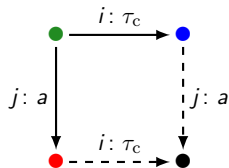
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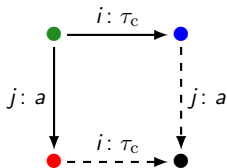


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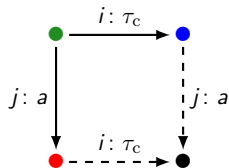
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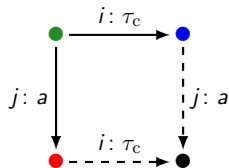
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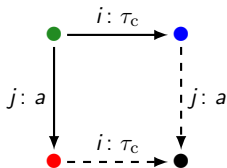
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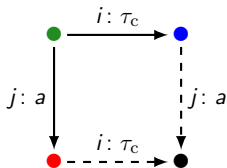
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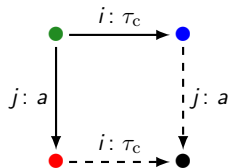
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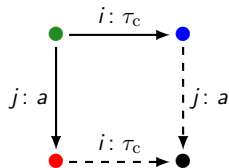
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We implemented:

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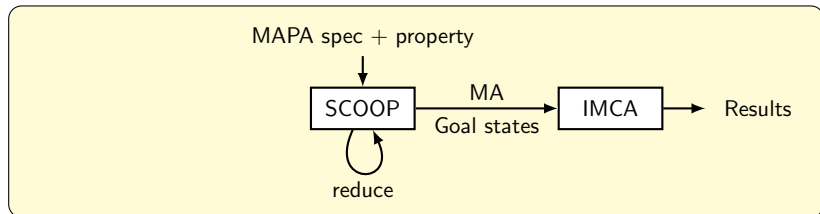
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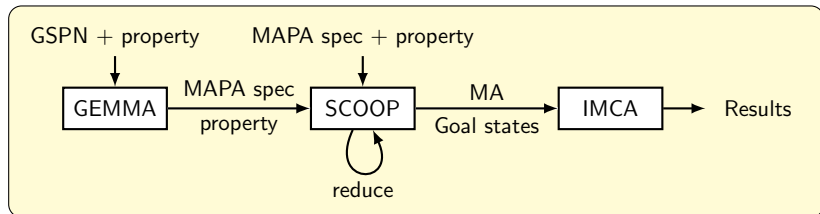
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Case studies

| Specification | Original state space | | | Reduced state space | | | Reduction | |
|---------------|----------------------|---------|---------|---------------------|--------|---------|-----------|------|
| | States | Trans. | IMCA | States | Trans. | IMCA | States | Time |
| leader-3-7 | 25,505 | 34,257 | 103.8 | 4,652 | 5,235 | 5.2 | 82% | 90% |
| leader-3-9 | 52,465 | 71,034 | 214.3 | 9,058 | 10,149 | 9.9 | 83% | 92% |
| leader-3-11 | 93,801 | 127,683 | 431.7 | 15,624 | 17,463 | 16.7 | 83% | 93% |
| leader-4-2 | 8,467 | 11,600 | 74.9 | 2,071 | 2,650 | 5.2 | 76% | 90% |
| leader-4-3 | 35,468 | 50,612 | 369.3 | 7,014 | 8,874 | 22.4 | 80% | 92% |
| leader-4-4 | 101,261 | 148,024 | 1,325.3 | 17,885 | 22,724 | 62.2 | 82% | 94% |
| poll-2-2-4 | 4,811 | 8,578 | 3.7 | 3,047 | 6,814 | 2.3 | 37% | 32% |
| poll-2-2-6 | 27,651 | 51,098 | 90.9 | 16,557 | 40,004 | 49.1 | 40% | 47% |
| poll-2-4-2 | 6,667 | 11,290 | 39.9 | 4,745 | 9,368 | 26.2 | 29% | 32% |
| poll-2-5-2 | 27,659 | 47,130 | 1,573.8 | 19,721 | 39,192 | 1,053.5 | 29% | 33% |
| poll-3-2-2 | 2,600 | 4,909 | 7.1 | 1,914 | 4,223 | 4.8 | 26% | 29% |
| poll-4-6-1 | 15,439 | 29,506 | 330.0 | 4,802 | 18,869 | 109.3 | 69% | 66% |
| poll-5-4-1 | 21,880 | 43,760 | 815.0 | 6,250 | 28,130 | 317.5 | 71% | 61% |
| grid-2 | 2,508 | 4,608 | 2.8 | 1,393 | 2,922 | 1.1 | 44% | 49% |
| grid-3 | 10,852 | 20,872 | 66.3 | 6,011 | 13,240 | 19.8 | 45% | 67% |
| grid-4 | 31,832 | 62,356 | 922.5 | 17,565 | 39,558 | 316.5 | 45% | 65% |

Conclusions and future work

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- It **preserves divergences** and is **closed under unions**
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Future work

- Develop even **more powerful reduction techniques**
- Define **partial-order reduction** as a **restriction** of confluence