Distributed Binary Decision Diagrams for Symbolic Reachability

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1 Introduction

- 2 High-performance networking
- 3 Distributed unique table
- 4 Fine-grained task-parallelism
- 5 Experimental evaluation
- 6 Conclusion

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Model checking: exhaustive analysis



image source: http://https://d.ibtimes.co.uk

Model checking: exhaustive analysis



Well-known limitation of model checking: state space explosions

image source: http://https://d.ibtimes.co.uk

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Fighting state space explosions: adding hardware



more memory: larger state spaces supported **more processors:** faster state space generation

image source: http://www.extremetech.com

Fighting state space explosions: problem representation



Partial order reduction



Bisimulation minimisation



SAT solving, IC3



Decision diagrams

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Fighting state space explosions: problem representation



Partial order reduction



SAT solving, IC3



Bisimulation minimisation



Binary Decision Diagrams

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BDDs: efficient representation of Boolean functions



Distributed symbolic reachability: challenges



Memory accesses dominate computational work

image sources: www.sqlskills.com (left) and www.qnap.com (right)

Distributed symbolic reachability: challenges



Memory accesses dominate computational work



Memory access patterns are often irregular

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Distributed symbolic reachability: challenges



Memory accesses dominate computational work



Memory access patterns are often irregular

Previous work achieves: Good space complexity, but limited time complexity

image sources: www.sqlskills.com (left) and www.qnap.com (right)

Most important design considerations for improvements (Ciardo, 2009)

Data-distribution and exploiting data-locality
2. Maintaining load balance
3. Reducing communication overhead

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Infiniband networking



- 1. Relatively cheap
- 2. Bandwidth: up to 100Gb/s

- 3. End-to-end latency: $\sim 1 \mu s$
- 4. Direct access to main-memory

image source: http://www.storagereview.com

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image source: http://www.storagereview.com

RDMA: Remote Direct Memory Access



- 1. CPU efficient
- 2. 20x faster than TCP over Ethernet
- 3. Zero-copy networking

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4. Kernel by-passing

image source: https://www.youtube.com/watch?v=dLw5bA5ziwU (modified)



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threads (fixed n)

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threads (fixed n)

private memory

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threads (fixed n)

private memory

global address space



threads (fixed n)

private memory

partitioned global address space

Shared array

Global view of a simple array of length n



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Partitioned shared array

Split up array into equal parts and distribute among threads



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Given a hash table T and a BDD node B

- find-or-put(B) returns found if $B \in T$
- find-or-put(B) inserts B and returns inserted if $B \notin T$
- find-or-put(B) returns full if $B \notin T$ and B cannot be inserted

Unique table implementation



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Unique table implementation



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Unique table implementation



- Linear probing
- Obtain chunks of buckets

Dynamically determine chunk size

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Obtain chunks of buckets

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- Dividing computational problems into smaller tasks
- Task is a basic unit of work and only depend on intermediate *subtasks*
- Each threads maintains a *task pool*

Private-deque work stealing

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- Performing reachability over well-known BEEM models
- Experiments performed on the DAS-5 cluster
 - We used up to 64 machines
 - Each machine has 16 CPU cores and 64GB internal memory
- Scaling along machines and threads per machine
- Measuring wall clock time and speedup

Scalability over BEEM models



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Conclusion

- Good time-efficiency (in addition to space-efficiency)
- Highest speedups observed: 45× with 64 machines
- Combined memory of 64 machines: 4TB on DAS-5

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Future work

- Performing reachability on very large models
- Experimenting with alternative decision diagrams
- Extending to full-blown CTL model checking
- Extending to GPU state space exploration